Active Mobility (Continental Automotive Singapore Pte Ltd — Exemption) Order 2021

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THE SCHEDULE

No. S 296

ACTIVE MOBILITY ACT 2017 (ACT 3 OF 2017)

ACTIVE MOBILITY (CONTINENTAL AUTOMOTIVE SINGAPORE PTE LTD — EXEMPTION) ORDER 2021

In exercise of the powers conferred by section 66 of the Active Mobility Act 2017, the Minister for Transport makes the following Order:

Citation and period in force

- 1.—(1) This Order is the Active Mobility (Continental Automotive Singapore Pte Ltd Exemption) Order 2021.
- (2) This Order is in force for the period between 1 May 2021 and 30 April 2022 (both dates inclusive).

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Definitions

2. In this Order —

"specified footpath" means any of the footpaths delineated by the black-coloured lines in the map set out in the Schedule;

"specified motor vehicle" means an autonomous motor vehicle that —

- (a) is known as a Corriere V1; and
- (b) has complied with the requirements of the test known as the Supervised Trial Readiness Assessment (Provisional Version) for Autonomous Vehicles on Public Paths that is jointly administered by the Authority and the Centre of Excellence for Testing & Research of Autonomous Vehicles NTU (CETRAN).

Exemption for driving specified motor vehicle

- 3. Section 16(1)(b) of the Act does not apply to an individual who drives a specified motor vehicle on a specified footpath under the following conditions:
 - (a) the individual (called in this Order the safety operator) is authorised by Continental Automotive Singapore Pte Ltd (UEN 199708326N) to drive the specified motor vehicle;
 - (b) the safety operator
 - (i) when the specified motor vehicle is in motion must be close enough to the specified motor vehicle to conduct an emergency stop if required;
 - (ii) when the specified motor vehicle is driven across a pedestrian crossing or an informal crossing must take manual control of the specified motor vehicle; and
 - (iii) when the specified motor vehicle is in motion with its autonomous system activated must only engage in the following activities:
 - (A) monitoring the movement of the specified motor vehicle and its surroundings;
 - (B) taking manual control of the specified motor vehicle when a failure of the autonomous system of the vehicle