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MOTOR VEHICLES
(THIRD-PARTY RISKS AND COMPENSATION) ACT
(CHAPTER 189)

MOTOR VEHICLES
(THIRD-PARTY RISKS AND COMPENSATION)
(OASIS TERRACES — EXEMPTION) NOTIFICATION 2021

ARRANGEMENT OF PARAGRAPHS

Paragraph

1. Citation and period in force
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 3. Exemption for use of specified motor vehicle
The Schedule
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In exercise of the powers conferred by section 23 of the Motor Vehicles (Third-Party Risks and Compensation) Act, the Minister for Transport makes the following Notification:

Citation and period in force

1.—(1) This Notification is the Motor Vehicles (Third-Party Risks and Compensation) (Oasis Terraces — Exemption) Notification 2021.

(2) This Notification is in force for the period between 7 January 2021 and 6 July 2021 (both dates inclusive).

Definitions

2. In this Notification —

“specified motor vehicle” means an autonomous motor vehicle that —

(a) is known as a Camello (model: CAMELLO); and

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- (b) has complied with the requirements of the test known as the Supervised Trial Readiness Assessment (Provisional Version) for Autonomous Vehicles on Public Paths that is jointly administered by the Centre of Excellence for Testing & Research of Autonomous Vehicles — NTU (CETRAN) and the Authority;

“specified road” means any road within the area bounded by the black line in the map set out in the Schedule.

Exemption for use of specified motor vehicle

3. Section 3 of the Act does not apply to, or in relation to, any individual who uses a specified motor vehicle on a specified road under the following conditions:

- (a) the individual (called in this Notification the safety operator) is authorised by OTSAW Digital Pte Ltd (UEN 201511868R) to use the specified motor vehicle;
- (b) the safety operator —
- (i) must, when the specified motor vehicle is in motion, be close enough to conduct an emergency stop if required;
 - (ii) must take manual control of the specified motor vehicle when it is driven across a pedestrian crossing or informal crossing; and
 - (iii) must only be engaged in the following activities when the specified motor vehicle is travelling in autonomous mode:
 - (A) monitor the movement of the specified motor vehicle and its surroundings;
 - (B) take manual control of the specified motor vehicle when a failure of the autonomous system of the vehicle or other emergency is detected;
- (c) the specified motor vehicle is only driven —
- (i) for the purpose of transporting goods;