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ACTIVE MOBILITY ACT 2017
(ACT 3 OF 2017)

ACTIVE MOBILITY
(GARDENS BY THE BAY — EXEMPTION)
ORDER 2020

ARRANGEMENT OF PARAGRAPHS

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In exercise of the powers conferred by section 66 of the Active Mobility Act 2017, the Minister for Transport makes the following Order:

Citation and period in force

1.—(1) This Order is the Active Mobility (Gardens by the Bay — Exemption) Order 2020.

(2) This Order is in force for the period between 16 November 2020 and 15 May 2021 (both dates inclusive).

Definitions

2. In this Order —

“specified motor vehicle” means an autonomous motor vehicle that —

- (a) is known as an auto-rider (model: NAVYA ARMA);
and

(b) has complied with the requirements of the test known as the Supervised Trial Readiness Assessment (Provisional Version) for Autonomous Vehicles on Public Paths that is jointly administered by the Centre of Excellence for Testing & Research of Autonomous Vehicles — NTU (CETRAN) and the Authority;

“specified person” means any of the following companies incorporated under the Companies Act (Cap. 50):

(a) Car Club Pte Ltd (UEN 200912077G);

(b) ST Engineering Land Systems Ltd (UEN 197100263N);

(c) Willers Pte Ltd (UEN 201816662N);

“specified shared path” means the part of the shared path specified in item 5 of Part 11 of the First Schedule to the Active Mobility (Shared Paths) Order 2018 (G.N. No. S 260/2018), and which is more particularly delineated by the black line in the map set out in the Schedule.

Exemption for specified motor vehicle drivers

3. Section 17(1) of the Act does not apply to an individual driving a specified motor vehicle on the specified shared path under the following conditions:

- (a) the individual (called in this Order the safety operator) is authorised by a specified person to drive the specified motor vehicle;
- (b) the safety operator must remain in the specified motor vehicle at all times when the vehicle is in motion;
- (c) the safety operator must only be engaged in the following activities while the specified motor vehicle is travelling in autonomous mode: